<u>Session IC. Robotics, Automation, and Control I</u> Moderator: Shih-Chung Kang (National Taiwan University)

15:00 #135. 4D-BIM based Optimal Flight Planning for Construction Monitoring Applications using Camera-equipped UAVs

Amir Ibrahim and Mani Golparvar-Fard

15:15 #99. Semantic Relation Detection Between Construction Entities to Support Safe Human-Robot Collaboration in Construction

Daeho Kim, Ankit Goyal, Alejandro Newell, Sanghyun Lee, Jia Deng and Vineet Kamat

15:30 #50. Task Allocation and Route Planning for Robotic Service Networks with Multiple Depots in Indoor Environments

Bharadwaj Mantha and Borja Garcia de Soto

- 15:45 #363. Vision-based Excavator Activity Recognition and Productivity Analysis in Construction Chen Chen, Zhu Zhenhua, Amin Hammad and Ahmed Walid
- 16:00 #334. The design of future construction lab

 Cheng Hsuan Yang, Tzong Hann Wu and Shih-Chung Kang
- 16:15 \$455. Digital Twins as the Next Phase of Cyber-Physical Systems in Construction Congwen Kan and Chimay Anumba
- 16:30 #192. Assessments of Intuition and Efficiency: Remote Control of the Arm of Excavator in Operational Space

Dong-Ik Sun, Sang-Keun Lee, Yong-Seok Lee, Sang-Ho Kim, Jun Ueda, Yong K Cho, Yong-Han Ahn and Chang-Soo Han